

60 系列(Series)-J60BH001 混合式步进电机(Hybrid Stepper Motor)



主要技术参数 Main technical parameters

引出线形式 Lead out line driver type

驱动方式 Drive model

工作制 Working system

步距角 Step angle

额定电压 Rated voltage/V D.C

保持转矩 Holding torque/N·m

自定位转矩 Detent torque/N·m

步距角误差 Step angle error

相电阻 Phase resistance/ Ω

相电感 Phase inductance/mH

牵出力矩 Pullout torque/N·m

重量 Weight/kg

四相5线 Four Phase 5-line

单极恒压双四相驱动 Unipolar constant voltage

double four best drive

真空短时 Short term vacuum

0.9°

24

≥ 1.6 @ A & B 通(Electrify) 1.3A

≤ 0.04

$\pm 5\%$

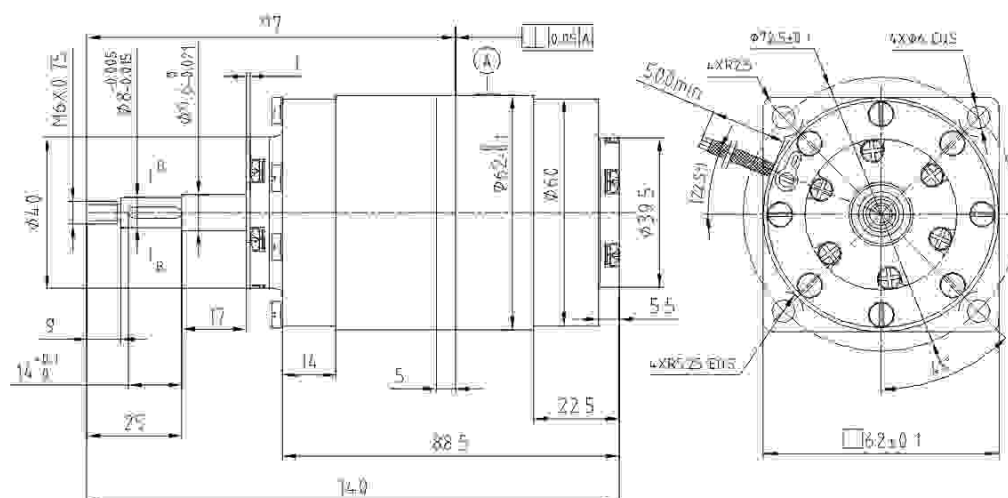
$18.7 \times (1 \pm 10\%)$

$40 \times (1 \pm 20\%)$

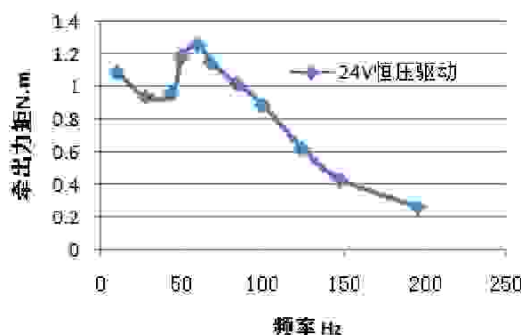
≥ 0.8 @ 50Hz

≤ 1.65

外形图(Outline Drawing)/mm

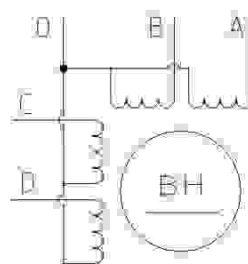


其他补充(Other Supplements)



牵出转矩特性(Pullout torque frequency characteristics)

电路图(Circuit Diagram)



引出线定义 Definition of lead wire

引出线标识 Identification of lead wire

A 相	B 相	C 相	D 相	公共点
A-phase	A-phase	A-phase	A-phase	Common
A	B	C	D	0